

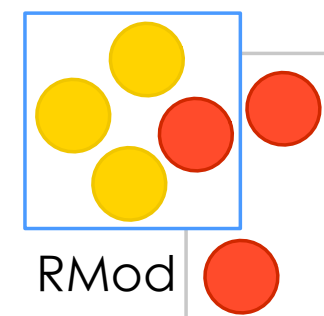
# Interpreter Register Autolocalisation

Improving the performance of efficient interpreters

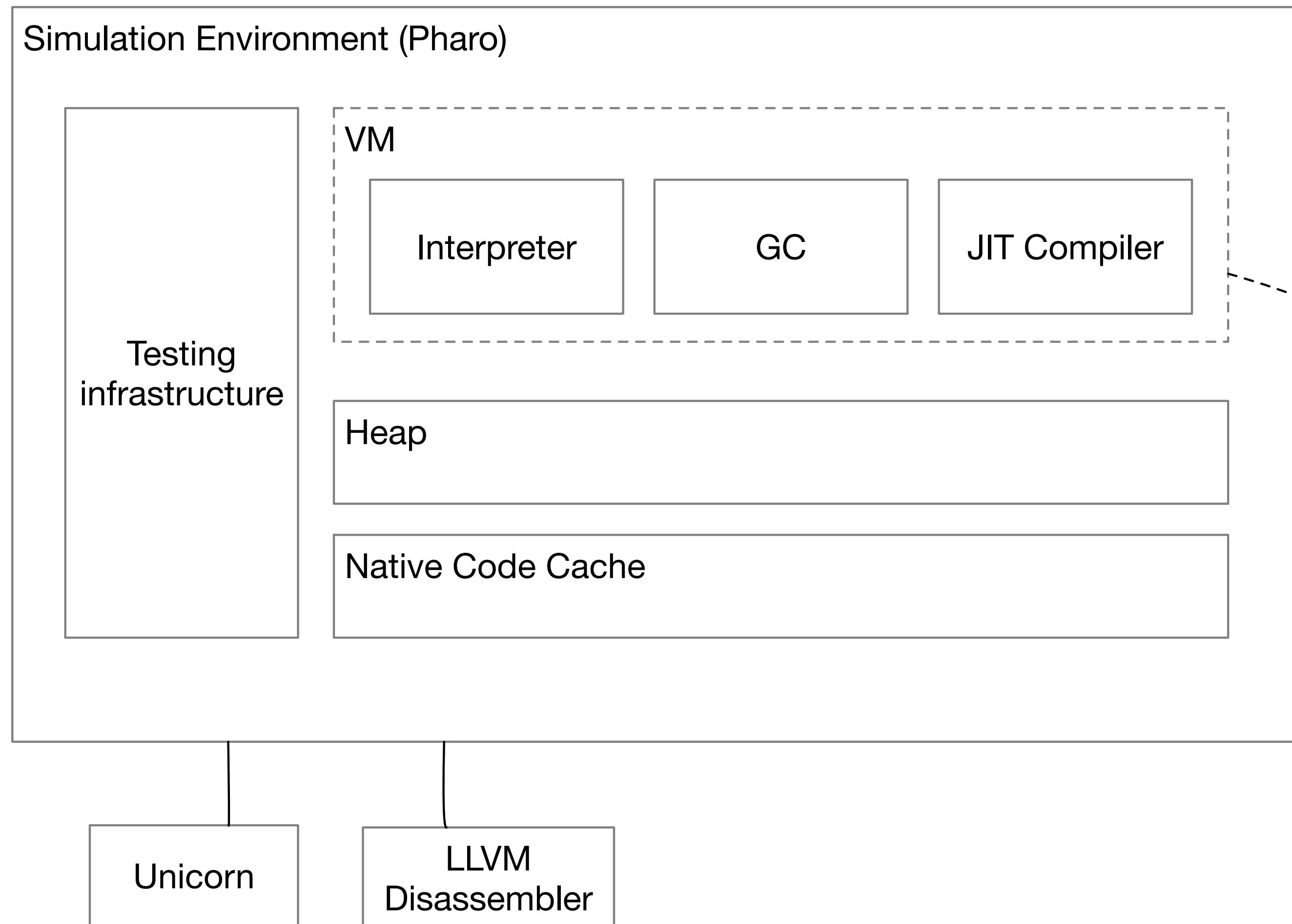
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**@guillep**



*Inria*



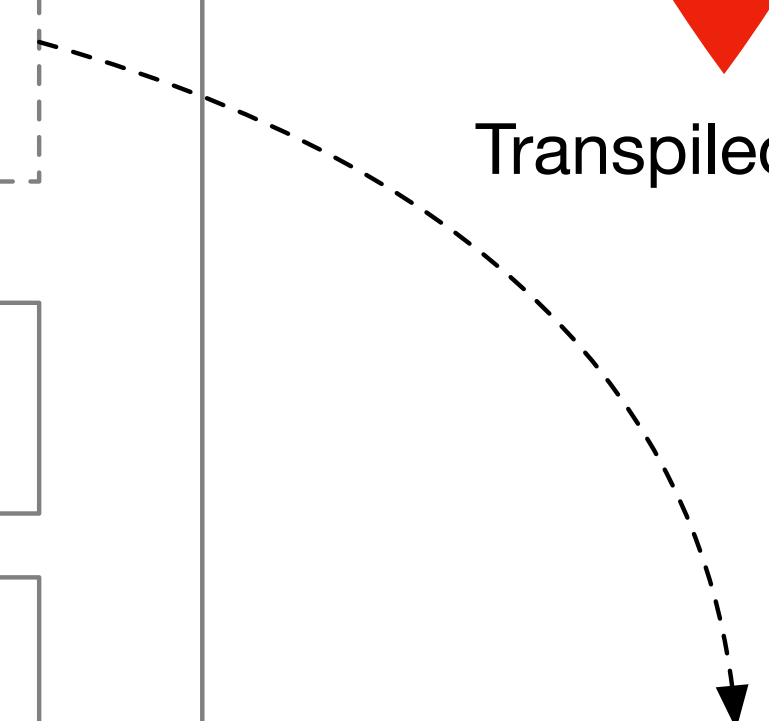
# The Slang VM Generator



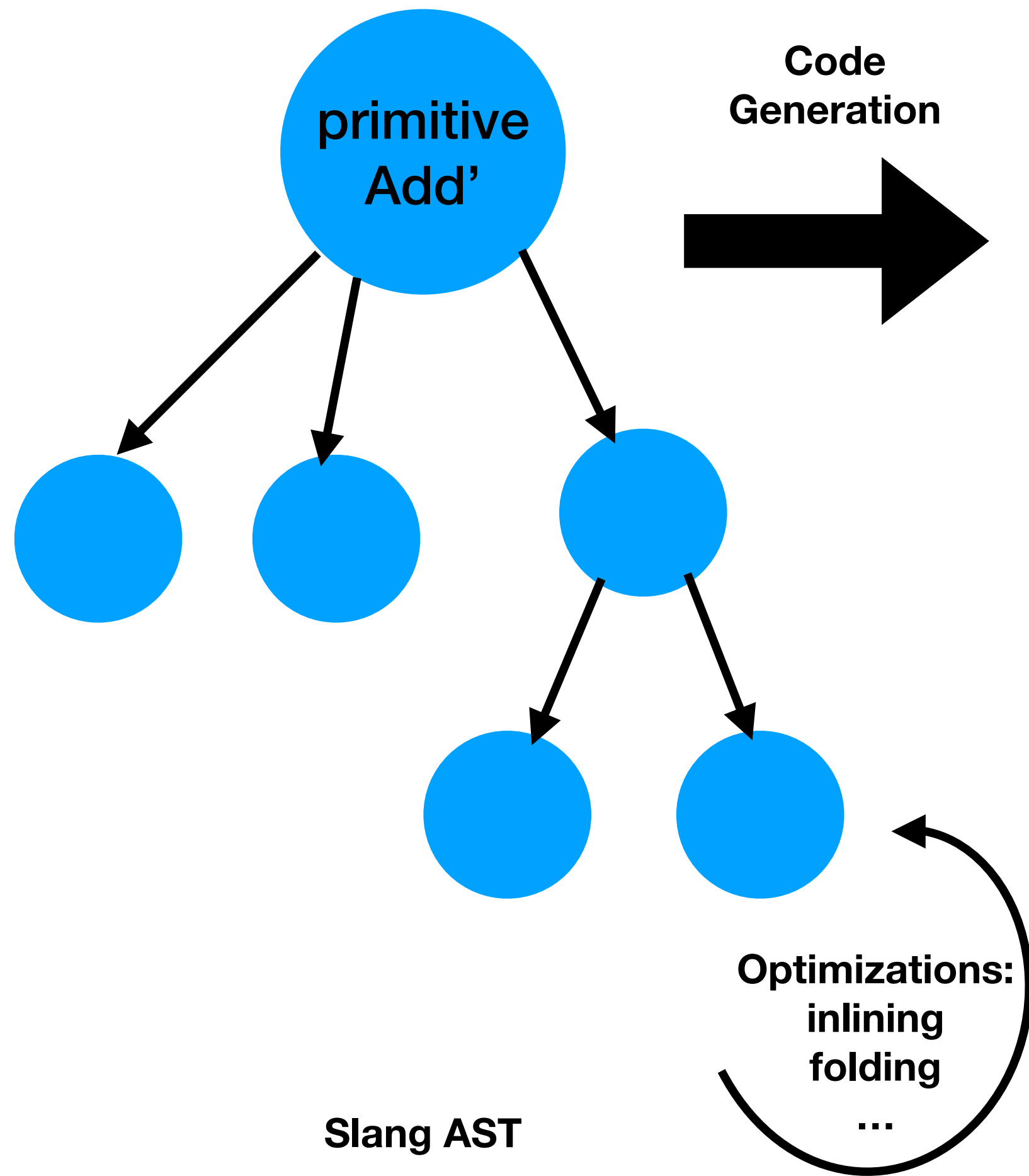
*Slang is Here!*

Transpiled to

Production VM (C)



# Slang Code Generation



```
/* InterpreterPrimitives>>#primitiveAdd */  
static void  
primitiveAdd(void)  
{  
    DECL_MAYBE_SQ_GLOBAL_STRUCT;  
    sqInt integerResult;  
    char *sp;  
  
    integerResult = (stackIntegerValue(1)) + (stackIntegerValue(0));  
    if (!GIV(primFailCode)) {  
        if (((((usqInt) integerResult) >> 60) + 1) & 15) <= 1) {  
            longAtput((sp = GIV(stackPointer) + ((2 - 1) * BytesPerWord)), (((usqInt) integerResult) >> 60) + 1);  
            GIV(stackPointer) = sp;  
        } else {  
            if (!GIV(primFailCode)) {  
                GIV(primFailCode) = 1;  
            }  
        }  
    }  
}
```

# The Slang VM Generator

## And the Pharo VM

```
interpret
self fetchNextBytecode.
[ true ] whileTrue: [
  self
  dispatchOn: currentBytecode
  in: BytecodeTable ].
^ nil
```

- Stack based VM
- Bytecode Dispatch table
  - 1 bytecode = 1 method
- Transformed in a C token threaded interpreter
  - + aggressive inlining

# The Slang VM Generator

## And the Pharo VM

**interpret**

```
self fetchNextBytecode.  
[ true ] whileTrue: [  
  self  
  dispatchOn: currentBytecode  
  in: BytecodeTable ].  
^ nil
```

**pushReceiverBytecode**

```
self fetchNextBytecode.  
self internalPush: self receiver
```

**pushBool: trueOrFalse**

```
<inline: true>  
self push: (objectMemory booleanObjectOf: trueOrFalse)
```

**internalAboutToReturn: resultOop through: aContext**

```
<inline: true>  
[...]  
self internalPush: resultOop  
[...]
```

- Stack based VM
  - Bytecode Dispatch table
    - 1 bytecode = 1 method
  - Transformed in a C token threaded interpreter
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# Pharo VM Manual Variable Localisation

## interpret

```
self fetchNextBytecode.  
[ true ] whileTrue: [  
  self  
  dispatchOn: currentBytecode  
  in: BytecodeTable ].  
^ nil
```

## pushReceiverBytecode

```
self fetchNextBytecode.  
self internalPush: self receiver
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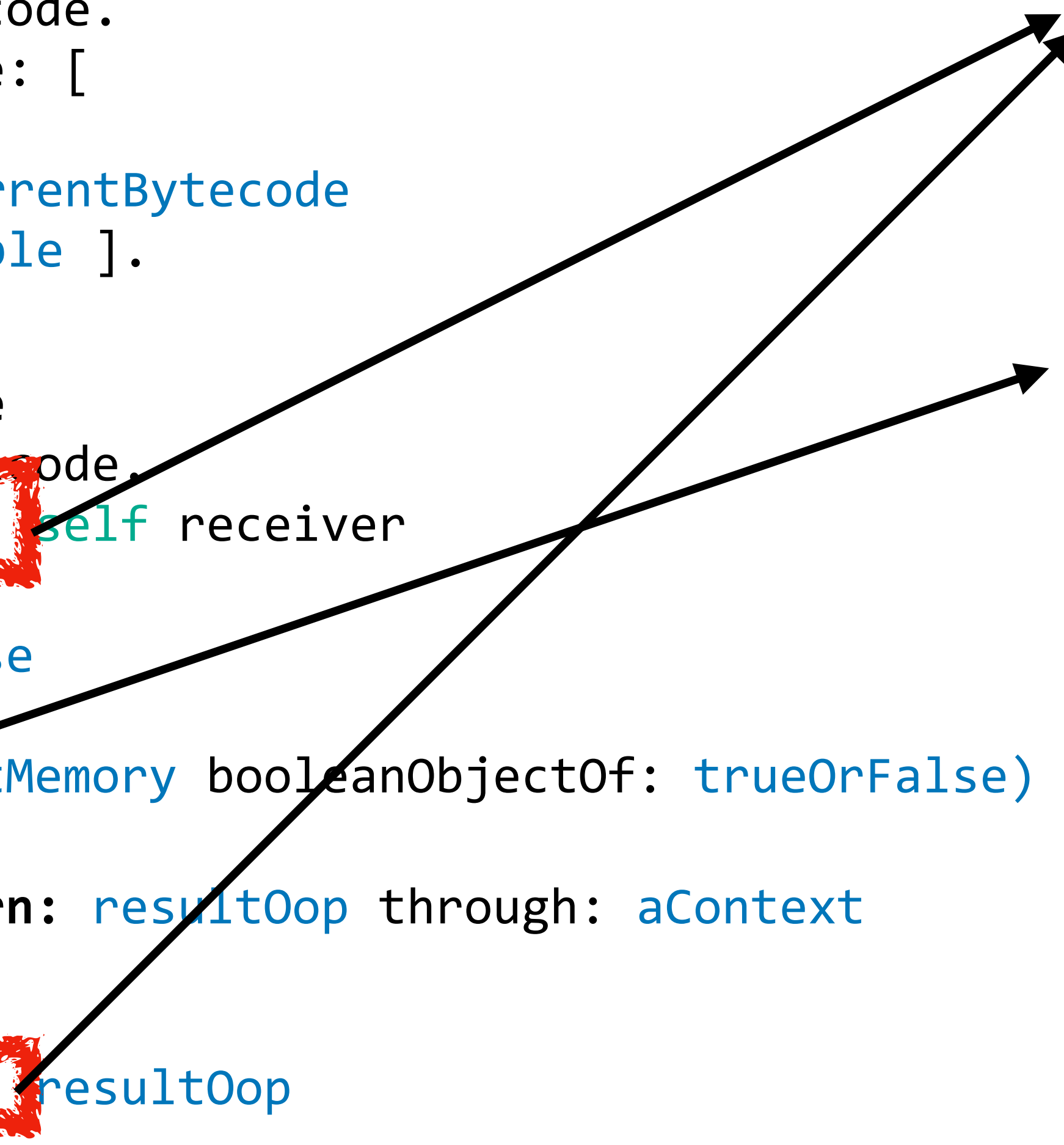
```
<inline: true>  
[...]  
self internalPush: resultOop  
[...]
```

## internalPush: aValue

```
localSP := localSP - bytesPerWord.  
self longAt: localSP put: aValue
```

## push: aValue

```
stackPointer := stackPointer - bytesPerWord.  
self longAt: stackPointer put: aValue
```



# Interpreter Register Localisation

- Variables critical to the interpreter efficiency (e.g., IP, FP, SP)
- Variables are duplicated and synchronized
  - a local version accessible to the interpreter loop  
=> meant to be optimised as registers
  - a global version accessible to the entire runtime  
=> meant to be used by slower routines

```
internalPush: aValue  
    localSP := localSP - bytesPerWord.  
    self longAt: localSP put: aValue
```

```
push: aValue  
    stackPointer := stackPointer - bytesPerWord.  
    self longAt: stackPointer put: aValue
```

# Is Interpreter Register Localisation Critical?

- Interpreter registers: interpreter variables with *frequent* usage  
e.g., IP, SP, FP, ??
  - **Intuition:** they are critical for performance
  - **Requirement:** need to be globally accessible for e.g.,
    - stack unwinding (exceptions, frame reification)
    - collection of GC roots
    - ...
- But! Manually copying values of interpreter registers:
  - *is error prone*
  - *does not allow to systematically verify our intuition*



# Automatic Localisation

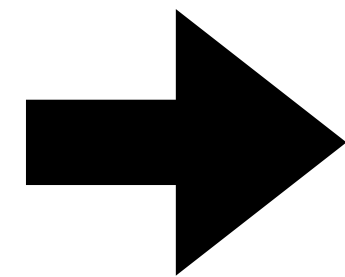
## Making Interpreter Registers Local at Translation Time

- An interpreter register (and using code) is defined only ***once***
- Automatic duplication on need
- Objectives:
  - Remove burden from VM developers
  - Allow systematic measure + specialisation of interpreter registers

# Automatic Localisation

## Making Interpreter Registers Local at Translation Time

```
var register1; // global
function interpret() {
  ...
  while(1) { switch(bytecode){
    // global reads and writes
    ... register1 ...
  } }
  return;
}
```



```
function interpret() {
  // localisation: copy from global
  var local_register1 := register1;
  ...
  while(1) { switch(bytecode){
    // local reads and writes
    ... local_register1 ...
  } }
  // globalisation: copy back to global
  register1 := local_register1;
  return;
}
```

# Automatic Localisation

## Synchronisation at Interpreter Exit Points

```
// inside the interpreter loop
...
register1 := local_register1; // globalisation
exit_point();
local_register1 := register1; // localisation
...

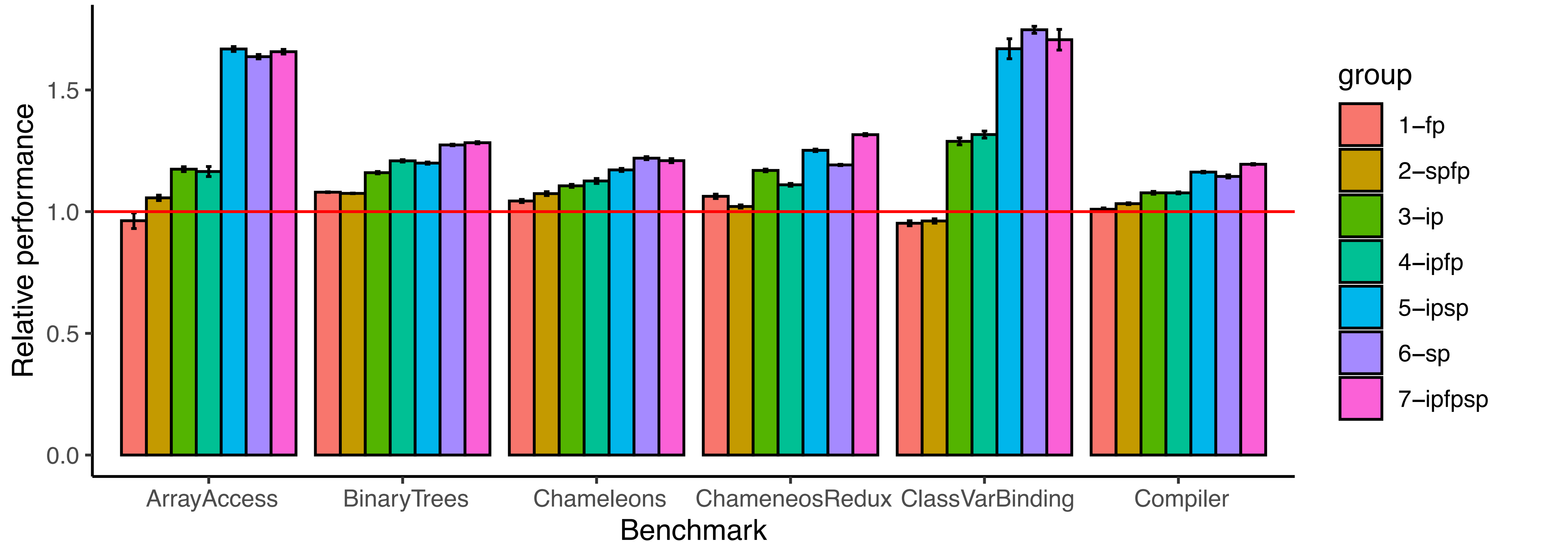
// outside the interpreter loop
function exit_point() {
  ... register1 ... // global reads and writes
}
```

### + Callgraph Optimisation:

Only synchronise variables used by the called function

# Some Benchmarks

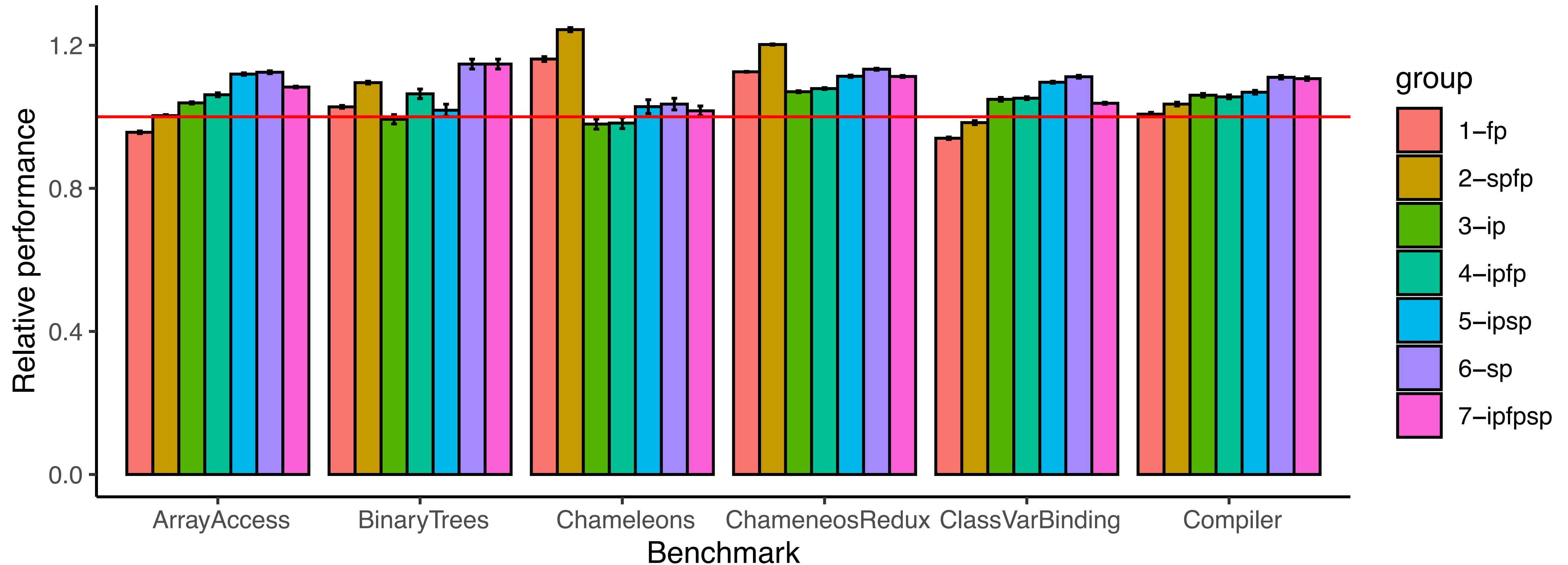
Intel x86-64



Averages of 100 iterations + stdev. Relative to baseline (no optimisation). Higher is better.

# Some Benchmarks

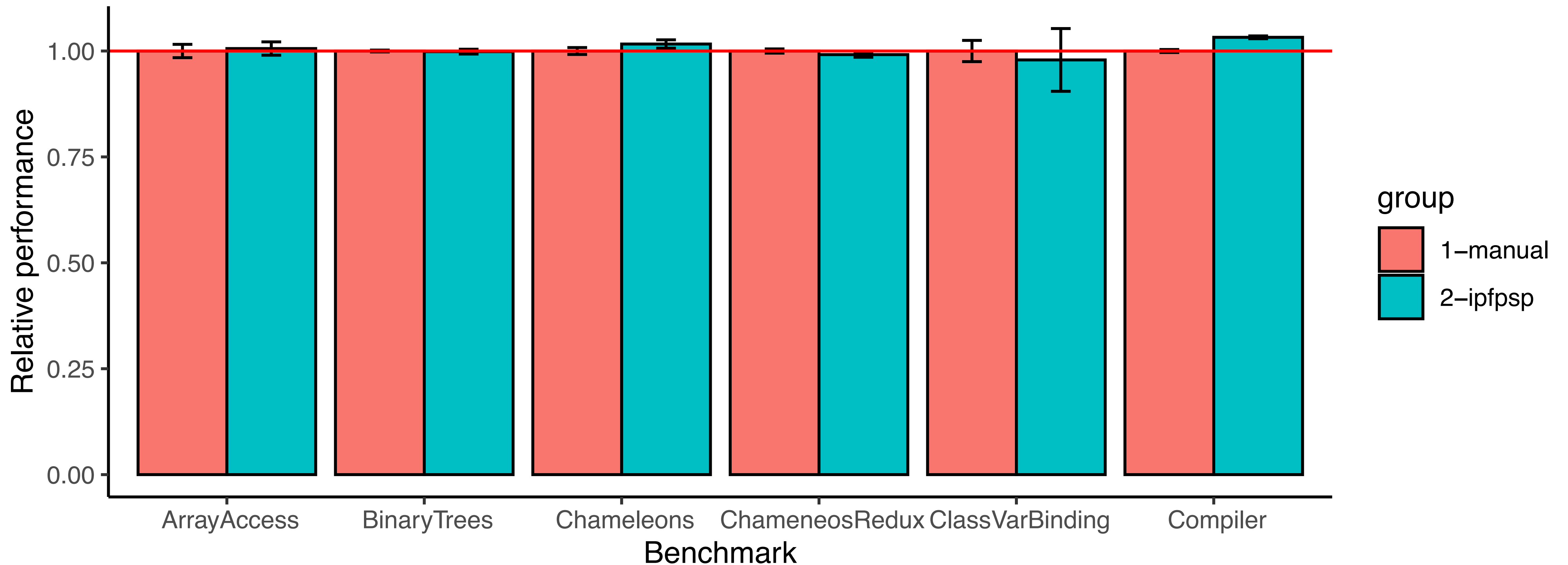
## ARM64 - Raspberry Pi



Averages of 100 iterations + stdev. Relative to baseline (no optimisation). Higher is better.

# Manual vs Automatic

Intel x86-64



Averages of 100 iterations. Relative to baseline (manual). Higher is better.

# Conclusion

- Interpreter register localisation yields **improvements of up to 1.92x**
- Not all interpreter registers impact performance in the same way (FP?)
- It can be done automatically without loss of performance!
  
- Future:
  - Study the impact in different architectures
  - Study the CPU and cache impact of these optimizations
  - Is there an optional combination for different setups?
  - Are there variables other than IP, FP, SP that should be considered interpreter registers?