**Advanced Object-Oriented Design** 

# About type and method lookup



http://www.pharo.org

#### Outline

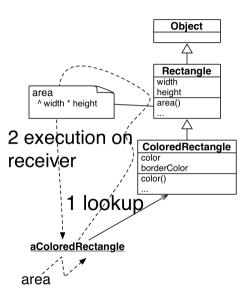
- Lookup (remember)
- Static type vs Dynamic type
- Type checker
- Method lookup



## **Message Sending**

**Sending** a **message** is a two-step process:

- 1. **look up** the **method** matching the message
- 2. execute this method on the **receiver**

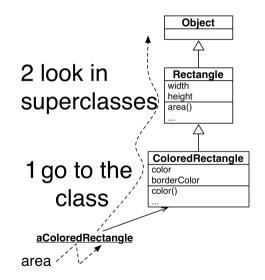




# **Method lookup**

The lookup starts in the **class** of the **receiver** then:

- if the method is defined in the class, it is returned
- otherwise the search continues in the superclass



#### It was the essence

Questions:

- How types influence (polute) this beautiful model?
- Static types, dynamic types, overloading

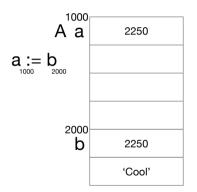


# The type of a variable

Let us a simple program model:

- a variable is a box with a label: its type.
- a variable contains a reference to objects.

A variable type indicates the kind of object the variable can refer to A a: we can put reference to objects of the class A (and subclasses)





During compilation

- A type checker is a tool that tries to make sure that correct objects are put in variables
- Using type information the type checker avoids that an unknown message is sent to an object



## Static vs. Dynamic Types

A a = new B();

- The static type of variable a is A i.e., the declared label of the box.
  - The static type never changes.
- The dynamic type of a is B i.e., the class of the object currently bound to a.
  - The dynamic type may change throughout the program.

a = new A();

Now the dynamic type is also A!



#### Static and dynamic types can be different

Consider:

A a = new B();

- The static type of variable a is A.
- The dynamic type of a is B





Pay attention method signatures also define static types

foo (A a){ } foo(new B());

static type of a is A, dynamic type of a is B



#### How do static and dynamic types interact?

```
class A {
   void m(A a) { println("A.m(A)"); }}
class B extends A {
   void m(B b) { println("B.m(B)"); }}
```

B b = new B(); A a = b;

What are the results of the invocations?

a.m(a); a.m(b); b.m(a); b.m(b);



#### How do static and dynamic types interact?

```
class A {
   void m(A a) { println("A.m(A)"); }}
class B extends A {
   void m(B b) { println("B.m(B)"); }}
```

Bb = new B(); Aa = b;

What are the results of the invocations?

a.m(a); A.m(A) a.m(b); A.m(A) b.m(a); A.m(A) b.m(b); B.m(B)

- Static types determine which message is sent.
- Dynamic types determine which method is called.

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## **Compilation vs. execution**

At compilation:

- First, the static type of the receiver determines which class we consider
- Second, does the class define the method?
- Third, does the static type of the arguments fit the static type of the parameter?
- Fourth, find the best fit

At execution:

• the lookup starts in the class of the receiver



# a.m(a)

```
class A {void m(A a) { println("A.m(A)"); }}
class B extends A {void m(B b) { println("B.m(B)"); }}
B b = new B(); A a = b;
```

- Step 1: receiver static type is A: we look in A
- Step 2: there is a method m
- Step 3: static type of a matches A a we will look for m(A a)

The dynamic type of a is B.

- The lookup starts in class B but looks for m(A a)
- > A.m(A)



# b.m(a)

```
class A {void m(A a) { println("A.m(A)"); }}
class B extends A {void m(B b) { println("B.m(B)"); }}
B b = new B(); A a = b;
```

- Step 1: the static type of b is  $\mathsf{B},$  so we look in  $\mathsf{B}$  and its superclass  $\mathsf{A}$
- Step 2: There is a method m (in fact two m(A a) and m(B b))
- Step 3: the static type of a is A we will look for m(A a)

The dynamic type of b is B.

- The lookup starts in class B and looks for m(A a)
- > A.m(A)



# **b.m(b)**

class A {void m(A a) { println("A.m(A)"); }}
class B extends A {void m(B b) { println("B.m(B)"); }}
B b = new B(); A a = b;

- Step 1: b static type is  $\mathsf{B},$  so we look in  $\mathsf{B}$  and its superclass  $\mathsf{A}$
- Step 2: There is a method m (in fact two m(A a) and m(B b))
- Step 3: the static type of b is  $\mathsf{B}$  we will look for  $m(\mathsf{B}\ b)$
- The lookup starts in class B and looks for m(B b)
- > B.m(B)



# a.m(b)

```
class A {void m(A a) { println("A.m(A)"); }}
class B extends A {void m(B b) { println("B.m(B)"); }}
B b = new B(); A a = b;
```

- Step 1: receiver static type is A: we only look in A
- Step 2: there is a method m
- Step 3: the static type of b is B but since A is a supertype of B this is ok we will look for m(A a)

The dynamic type of a is B

- The lookup starts in class B and looks form(A a)
- > A.m(A)





class A {void m(A a) { println("A.m(A)"); }}
class B extends A {void m(B b) { println("B.m(B)"); }}
B b = new B(); A a = b; C c = new C;

- Step 1: We look only in A
- Step 2: there is a method m
- Step 3: C the static type of c does not match A there is no subtype relations

Does not compile!



#### Conclusion

- Examples used so far were simple
- By careful with static types, it can get tricky
- Check lecture on overloading
- Check lectures on interfaces



#### A course by

#### S. Ducasse, G. Polito, and Pablo Tesone





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